Placer River Trail Bridge Inspection Using Small Unmanned Aircraft Systems



Fall Tactical Fire Remote Sensing Advisory Committee October 29, 2015 Boise, Idaho

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GOALS

- 1) Use a UAS to collect high resolution natural color stereo pair and video imagery of the Placer River Trail Bridge to evaluate as an alternative or supplemental tool to traditional structure inspection techniques
- 2) Evaluate dense Structure from Motion (dSfM) image processing techniques to produce a measurable 3D wireframe bridge model
- 3) Compare dSfM point cloud to laser scanner point cloud



COOPERATION

Forest Service Region 10, Washington Office, and Glacier Ranger District, Chugach National Forest: implementation, planning, coordination

University of Alaska Fairbanks: UAS, pilots, lead researcher

George Mason University: data collection, processing, analysis







LOCATION

89-km (55 miles) south of Anchorage

Anchorage

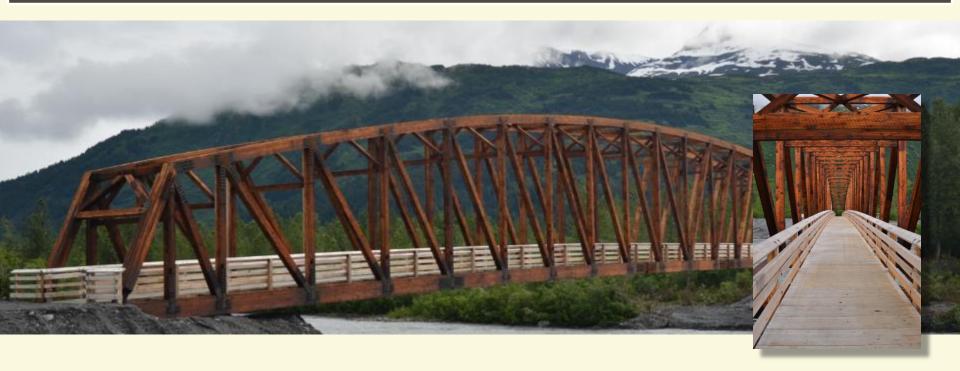


Girdwood

MOUNT ALTESNA ALTEXKA

Placer River Trail Bridge

ABOUT THE BRIDGE



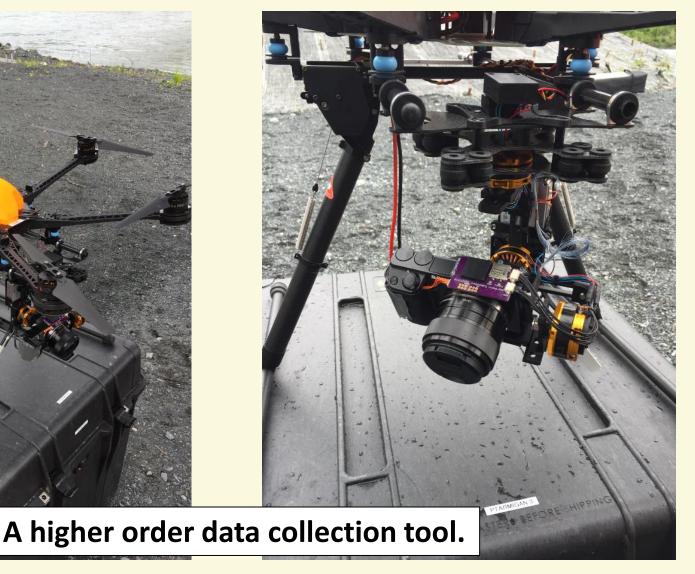
- Longest clear span, glued-laminated, timber truss pedestrian bridge in North America at 280 feet
- Anticipated operational service life of 75-years
- Completed in July 2013
- Managed for pedestrian use (Glacier Ranger District)
- Remote site; accessible via Alaska Railroad

UAS PLATFORM

Purpose built hexacopter "Ptarmigan" Based on DJI S800 airframe



Gyrostabilized Sony Nex7 and GoPro ~20 min/flight (LiPo batteries)



UAS PLATFORM

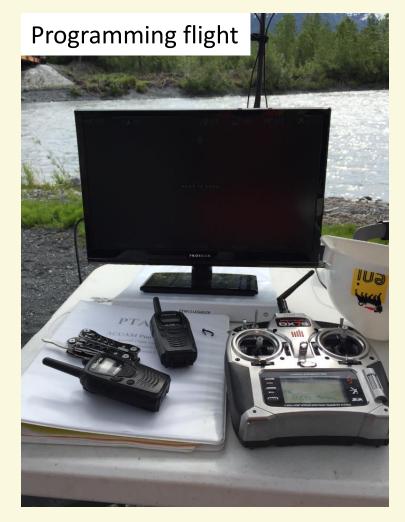
Two pilots (one acting as spotter) and generator to power equipment <1 hr to set up and have safety briefing

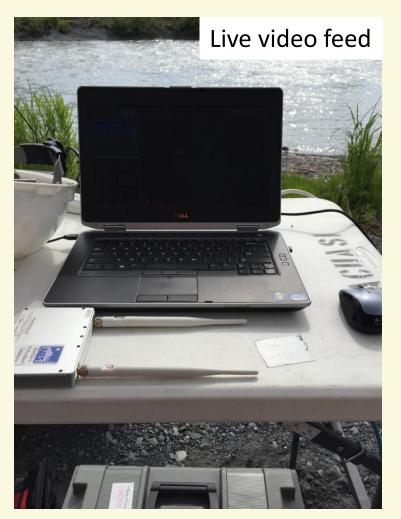


UAS CONTROL

Base station

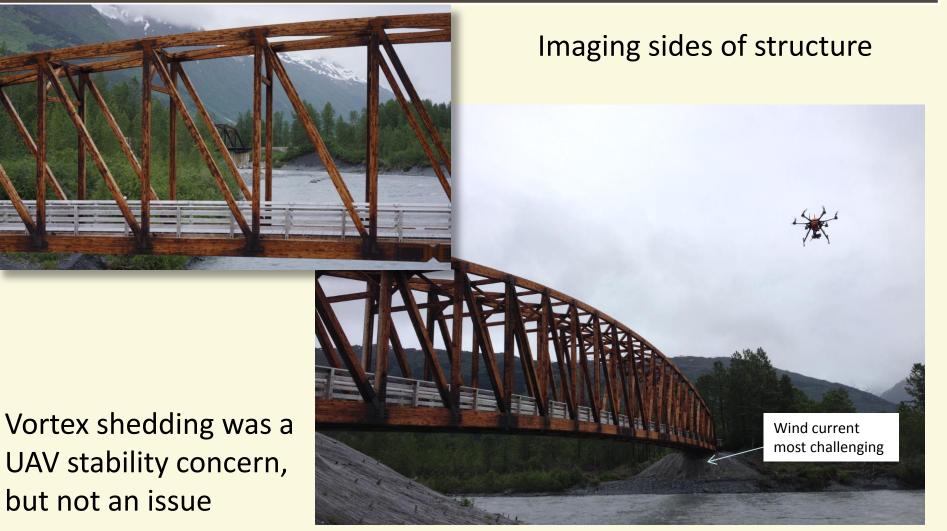
Programmable flights GPS or GNSS signal essential (if lost, return home function) Live video feed





FARO Focus laser scanner set up in 12 locations









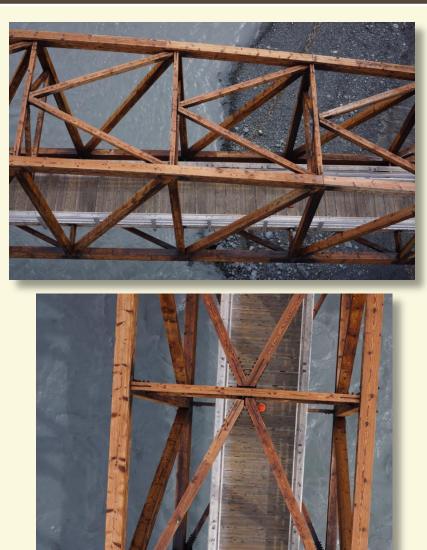
Upward-looking GoPro video imaging beneath structure

Lighting is a minor issue

Mostly manual control

Imaging top of structure





A CAN

Type of Data	Sensor Type	No. of Images/Scans	Size (GB)	Note
Imaging	Nikon D800E	2222	34.9	Ground-based imagery
	Sony Alpha NEX-7	2626	24.7	UAS-based imagery
Video	GoPro	10	7.57	-
Laser scanning	FARO Focus ^{3D}	24	4.26	-
3D Point Clouds	-	5	13.71	-

Table 1 Summary of Data Acquisition Mission

- Still frames collected with nominal 90% overlap
- >90% imagery useable for SfM (Photoscan Pro)
- ~4 hrs total flight time

90GB and 5000 images, video, and laser scans



Bridge plans used for point of reference and to assist with autopilot navigation

Data Analysis

DATA ANALYSIS

<u>Goals</u>

- Recreate flaws
- View underside of deck
- Track long-term camber/motion

Challenges

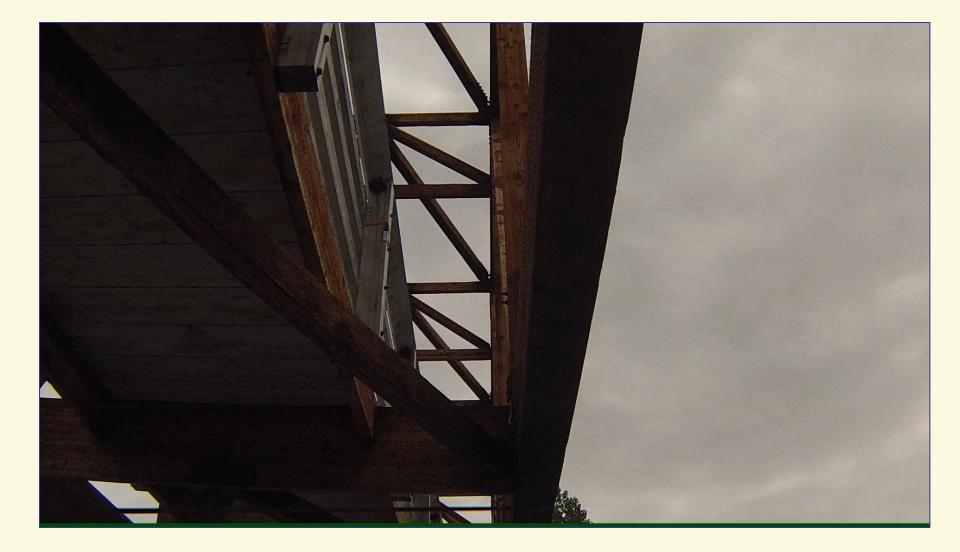
- Massive data set
- Confusing data
- Image degradation
- High contrast scene

RECREATING FLAWS

Gap between end of kerf plate and sawn kerf in brace

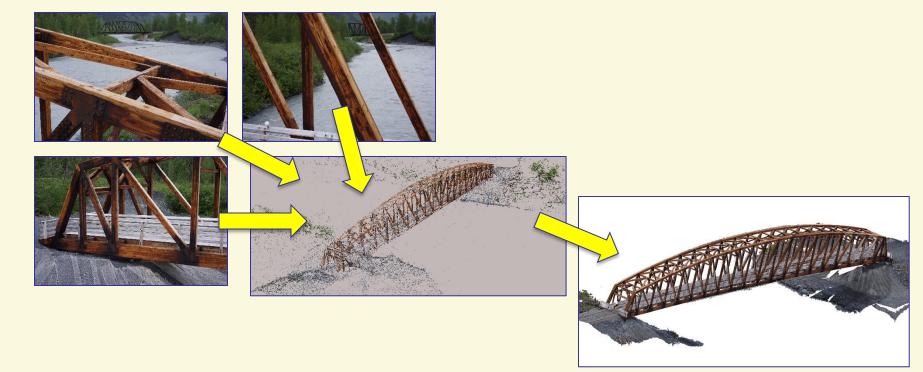


DECK UNDERSIDE



BUILDING A MEASUREABLE MODEL

- Images to 3D model: Structure-from-Motion
 - triangulate features across image set
 - Software: Photoscan and SURE
- Small details, big model

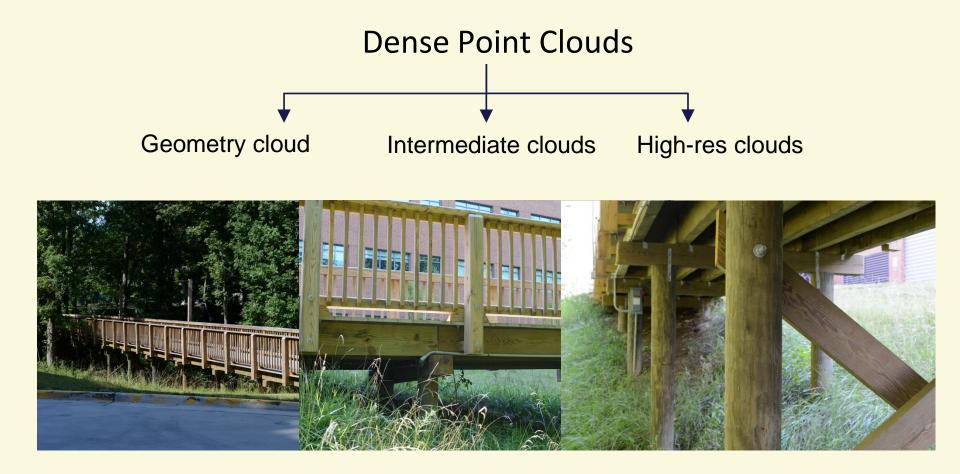


HPCG MODEL GENERATION

- 1. Separate clouds for big and small details
 - Image capture plan is critical!
- 2. Merge the sparse models
- 3. Generate dense reconstruction
 - SURE vs Photoscan

GeometryIntermediateHigh-resCloudCloudsClouds

HPCG MODEL GENERATION



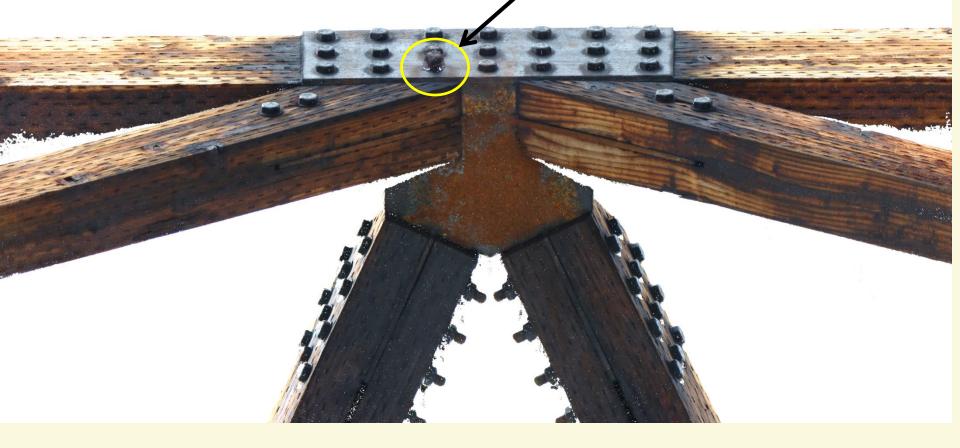
RESULTS

- 500 hours of computation time
- 14 billion points
- Need good rendering support!

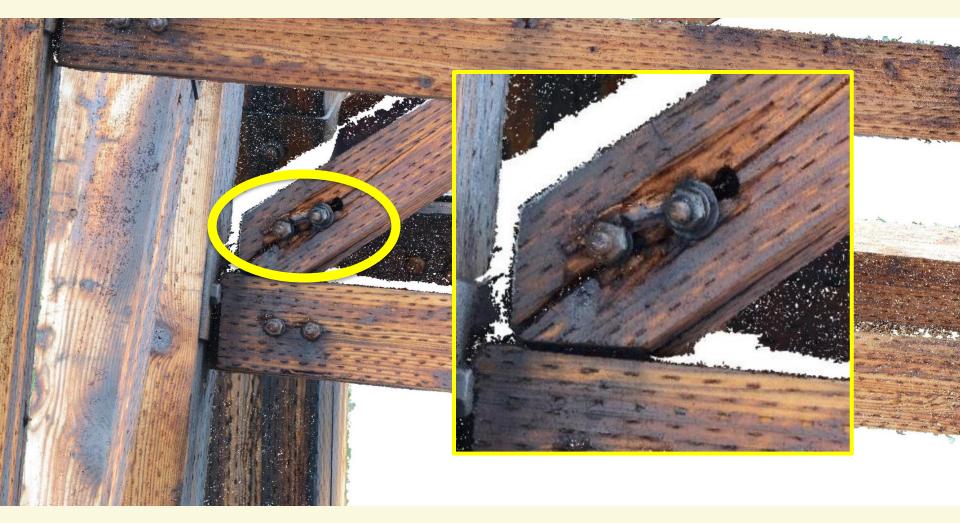


RECONSTRUCTING FLAWS

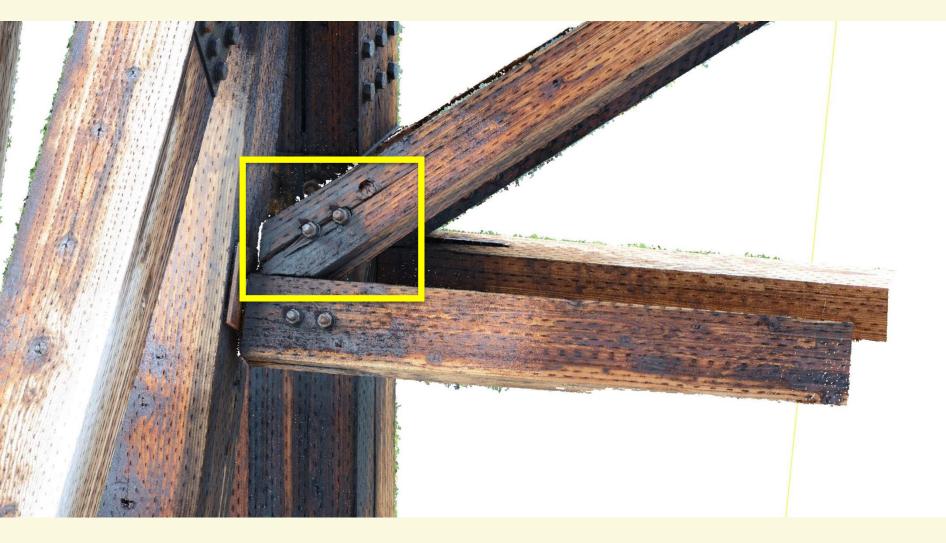
Bolt head not flush with plate



POINT CLOUD RECONSTRUCTION



POINT CLOUD RECONSTRUCTION



POINT CLOUD RECONSTRUCTION



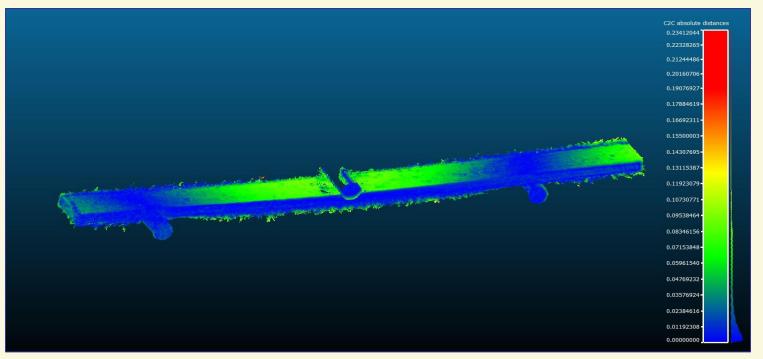
CAMBER TRACKING

- As bridge ages, it sags
 does it age gracefully?
- Rate of sag is a health indicator
- Required level of accuracy ≤ 10mm



CAMBER TRACKING

- Point cloud deviation analysis
- Models from repeated inspections
- Accuracy based on cloud resolution
- Sub-millimeter measurement is possible



- Angle of incidence for most of the structure is achievable only with a UAS
- A UAS is an effective means to obtain thousands of high resolution (~0.5cm) stereo pair images of a structure in a short amount of time
- For this bridge, and with low wind speeds, vortex shedding was a minor, surmountable issue





- 4) Dense Structure from Motion (dSfM) image processing techniques are [currently] the most effective way to produce highly detailed and accurate measureable **multispectral** 3D models in a short period. Depending on collection parameters, dSfM can produce a denser point cloud than lidar.
- 5) For this remote location, privacy was not a concern
- 6) Proposed FAA rules are sufficient for this type operation



- Proof-of-concept costs are not reflective of future costs; costs will decrease for subsequent projects
- 8) The mission was successful and is replicable for other similar projects



- 9) Could not get interior of bridge with UAS as it was too bulky to operate safely; a hand-held Nikon D800E was used to collect stereo imagery for dSfM processing
- 10) Takes a powerful computer and several weeks of processing to produce accurate and detailed dSfM models



CONCLUSIONS

A sUAS minimizes the time spent on site and increases safety by removing potential points of failure - such as suspended platforms, ladders, and harnesses - and potentially dangerous situations from the conventional inspection equation

Proposed FAA rules will be sufficient for 90% of Forest Service sUAS operations across multiple disciplines

Cost of using sUAS for project work, such as structure inspections, **will decrease** as Forest Service sUAS policy evolves and methods mature

A sUAS is a **higher order data collection tool** that needs to be more effectively utilized by the Forest Service

NEXT STEPS

- **1) Science**: processing, analysis, reporting, technology development
- 2) Policy Development: Forest Service and FAA
- 3) Effective Implementation: Guidelines and new projects



